Gear Trains Formulas...





Gear Trains Formulas

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List of 13 Gear Trains Formulas

Gear Trains 🕑

1) Braking or Holding Torque on Fixed Member given Input Torque 🕑

fx
$$T = T_1 \cdot \left(\frac{\omega_1}{\omega_2} - 1\right)$$

ex $-2.833333N^*m = 17N^*m \cdot \left(\frac{95.492966 \text{rev/min}}{114.591559 \text{rev/min}} - 1\right)$
2) Holding or Braking or Fixing Torque on Fixed Member \checkmark
fx $T = T_1 \cdot \left(\frac{N_1}{N_2} - 1\right)$
ex $196.6283N^*m = 17N^*m \cdot \left(\frac{1400 \text{rev/min}}{700 \text{rev/min}} - 1\right)$
3) Holding or Braking or Fixing Torque on Fixed Member given Input and

3) Holding or Braking or Fixing Torque on Fixed Member given Input and Output Torque

fx
$$\mathrm{T}=-(\mathrm{T}_1+\mathrm{T}_2)^{-1}$$

ex
$$-35N^*m = -(17N^*m + 18N^*m)$$



 N_1

4) Output Torque on Driven Member given Angular Speed of Driven and Driver

$$\begin{array}{l} \textbf{K} \quad T_2 = T_1 \cdot \frac{1}{N_2} \\ \textbf{K} \quad 213.6283N^*m = 17N^*m \cdot \frac{1400 \text{rev/min}}{700 \text{rev/min}} \\ \textbf{5} \end{array} \\ \textbf{Output Torque or Resisting or Load Torque on Driven Member } \textbf{K} \\ \textbf{K} \quad T_2 = -T_1 \cdot \frac{\omega_1}{\omega_2} \\ \textbf{K} \quad T_2 = -T_1 \cdot \frac{\omega_1}{\omega_2} \\ \textbf{K} \quad T_2 = -T_1 \cdot \frac{\omega_1}{\omega_2} \\ \textbf{K} \quad 1.4.166667N^*m = -17N^*m \cdot \frac{95.492966 \text{rev/min}}{114.591559 \text{rev/min}} \\ \textbf{G} \quad \textbf{Speed Ratio of Compound Gear Train } \textbf{K} \\ \textbf{K} \quad \textbf{I} = \frac{P_d}{P'_d} \\ \textbf{K} \quad \textbf{I} = \frac{P_d}{P'_d} \\ \textbf{K} \quad \textbf{I} = \frac{P_d}{P'_d} \\ \textbf{K} \quad \textbf{I} = \frac{T_dr}{T_d} \\ \textbf{K} \quad \textbf{I} = \frac{T_dr}{T_d} \\ \textbf{K} \quad \textbf{I} = \frac{20}{15.6} \\ \textbf{K} \quad \textbf{K} \quad \textbf{K} \quad \textbf{K} \quad \textbf{K} \quad \textbf{K} \\ \textbf{K} \quad \textbf{K} \quad \textbf{K} \quad \textbf{K} \quad \textbf{K} \\ \textbf{K} \quad \textbf{K} \quad \textbf{K} \quad \textbf{K} \quad \textbf{K} \quad \textbf{K} \\ \textbf{K} \quad \textbf{K} \quad \textbf{K} \quad \textbf{K} \quad \textbf{K} \quad \textbf{K} \quad \textbf{K} \\ \textbf{K} \quad \textbf{K} \\ \textbf{K} \quad \textbf{K} \\ \textbf{K} \quad \textbf{K} \quad$$



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Gear Trains Formulas...

8) Train Value given Speed of Follower and Driver 🕑



$$32 \mathrm{rev}/\mathrm{min}$$

9) Train Value of Compound Gear Train given product of Teeth on Driven and Driver Gear

fx
$$T_v = rac{P'_d}{P_d}$$
 ex $1.6875 = rac{27}{16}$

10) Train Value of Compound Gear Train given Speed of Driven and Driver Gear

fx
$$T_{
m v}=rac{
m N_n}{
m N_{d'}}$$
 ex $0.785714=rac{22 {
m rev}/{
m min}}{28 {
m rev}/{
m min}}$





Open Calculator

Open Calculator

11) Velocity Ratio 🗹



fx
$$i = \frac{N_n}{N_d}$$
, Open Calculator

$$\boxed{0.785714 = \frac{22 \mathrm{rev}/\mathrm{min}}{28 \mathrm{rev}/\mathrm{min}}}$$

13) Velocity Ratio of Compound Belt Drive given Product of Diameter of Driven





Variables Used

- i Velocity Ratio
- **N₁** Angular Speed of Driving Member in RPM (*Revolution per Minute*)
- **N**₂ Angular Speed of Driven Member in RPM (*Revolution per Minute*)
- N_d Speed of Driver (Revolution per Minute)
- **N**_{d'} Speed of First Driver (*Revolution per Minute*)
- N_f Speed of Follower (*Revolution per Minute*)
- Nn Speed of Last Driven Pulley (Revolution per Minute)
- P1 Product of Diameters of Drivers
- P2 Product of Diameters of Drivens
- Pd Product of Number of Teeth on Driven
- P'd Product of Number of Teeth on Drivers
- **T** Total Torque (Newton Meter)
- **T₁** Input Torque on Driving Member (*Newton Meter*)
- **T**₂ Output Torque or Load Torque on Driven Member (*Newton Meter*)
- T_d Number of Teeth on Driven
- Tdr Number of Teeth on Driver
- T_v Train Value
- ω₁ Angular Speed of Driving Member (*Revolution per Minute*)
- ω₂ Angular Speed of Driven Member (*Revolution per Minute*)



Constants, Functions, Measurements used

- Measurement: Frequency in Revolution per Minute (rev/min) Frequency Unit Conversion
- Measurement: Angular Velocity in Revolution per Minute (rev/min) Angular Velocity Unit Conversion
- Measurement: Torque in Newton Meter (N*m) Torque Unit Conversion





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