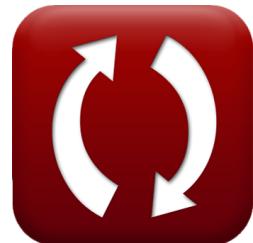


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# DC Motor Characteristics Formulas

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# List of 26 DC Motor Characteristics Formulas

## DC Motor Characteristics ↗

### 1) Angular Speed given Electrical Efficiency of DC Motor ↗

$$fx \quad \omega_s = \frac{\eta_e \cdot V_s \cdot I_a}{\tau_a}$$

[Open Calculator ↗](#)

$$ex \quad 52.1788 \text{rev/s} = \frac{0.8 \cdot 240V \cdot 0.724A}{0.424N*m}$$

### 2) Armature Current given Electrical Efficiency of DC Motor ↗

$$fx \quad I_a = \frac{\omega_s \cdot \tau_a}{V_s \cdot \eta_e}$$

[Open Calculator ↗](#)

$$ex \quad 0.723989A = \frac{52.178 \text{rev/s} \cdot 0.424N*m}{240V \cdot 0.8}$$

### 3) Armature Current of DC Motor ↗

$$fx \quad I_a = \frac{V_a}{K_f \cdot \Phi \cdot \omega_s}$$

[Open Calculator ↗](#)

$$ex \quad 0.724496A = \frac{320V}{1.135 \cdot 1.187Wb \cdot 52.178 \text{rev/s}}$$



## 4) Armature Torque given Electrical Efficiency of DC Motor

$$fx \quad \tau_a = \frac{I_a \cdot V_s \cdot \eta_e}{\omega_s}$$

[Open Calculator !\[\]\(cbe80b694ebd74fcfe136a095b608235\_img.jpg\)](#)

$$ex \quad 0.424006N*m = \frac{0.724A \cdot 240V \cdot 0.8}{52.178rev/s}$$

## 5) Armature Torque given Mechanical Efficiency of DC Motor

$$fx \quad \tau_a = \eta_m \cdot \tau$$

[Open Calculator !\[\]\(3e2231b1ad3ca8da8658228c00dd08e0\_img.jpg\)](#)

$$ex \quad 0.4236N*m = 0.60 \cdot 0.706N*m$$

## 6) Back EMF Equation of DC Motor

$$fx \quad E_b = \frac{n \cdot \Phi \cdot Z \cdot N}{60 \cdot n_{||}}$$

[Open Calculator !\[\]\(0d5ec72f61334709c3fc9450209b754f\_img.jpg\)](#)

$$ex \quad 24.94334V = \frac{4 \cdot 1.187Wb \cdot 14 \cdot 1290rev/min}{60 \cdot 6}$$

## 7) Constant Losses given Mechanical Loss

$$fx \quad C_{loss} = P_{core} + L_m$$

[Open Calculator !\[\]\(b64b40baaee5acddc1eab8538ba84754\_img.jpg\)](#)

$$ex \quad 15.9W = 6.8W + 9.1W$$



## 8) Converted Power given Electrical Efficiency of DC Motor ↗

$$fx \quad P_{\text{conv}} = \eta_e \cdot P_{\text{in}}$$

[Open Calculator ↗](#)

$$ex \quad 62.4W = 0.8 \cdot 78W$$

## 9) Core Loss given Mechanical Loss of DC Motor ↗

$$fx \quad P_{\text{core}} = C_{\text{loss}} - L_m$$

[Open Calculator ↗](#)

$$ex \quad 6.8W = 15.9W - 9.1W$$

## 10) DC Motor Frequency given Speed ↗

$$fx \quad f = \frac{n \cdot N}{120}$$

[Open Calculator ↗](#)

$$ex \quad 4.502949\text{Hz} = \frac{4 \cdot 1290\text{rev/min}}{120}$$

## 11) Electrical Efficiency of DC Motor ↗

$$fx \quad \eta_e = \frac{\tau_a \cdot \omega_s}{V_s \cdot I_a}$$

[Open Calculator ↗](#)

$$ex \quad 0.799988 = \frac{0.424\text{N*m} \cdot 52.178\text{rev/s}}{240\text{V} \cdot 0.724\text{A}}$$



## 12) Input Power given Electrical Efficiency of DC Motor

**fx**  $P_{in} = \frac{P_{conv}}{\eta_e}$

[Open Calculator !\[\]\(e2376d476d06eb31946dc01a69a4403a\_img.jpg\)](#)

**ex**  $78W = \frac{62.4W}{0.8}$

## 13) Machine Construction Constant of DC Motor

**fx**  $K_f = \frac{V_s - I_a \cdot R_a}{\Phi \cdot N}$

[Open Calculator !\[\]\(0b5e7e25e8775f7e7e80906ada4f0021\_img.jpg\)](#)

**ex**  $1.135516 = \frac{240V - 0.724A \cdot 80\Omega}{1.187Wb \cdot 1290\text{rev/min}}$

## 14) Magnetic Flux of DC Motor

**fx**  $\Phi = \frac{V_s - I_a \cdot R_a}{K_f \cdot N}$

[Open Calculator !\[\]\(bd3b31712ad9bab5a241210fa6925cdd\_img.jpg\)](#)

**ex**  $1.187539Wb = \frac{240V - 0.724A \cdot 80\Omega}{1.135 \cdot 1290\text{rev/min}}$

## 15) Mechanical Efficiency of DC Motor

**fx**  $\eta_m = \frac{\tau_a}{\tau}$

[Open Calculator !\[\]\(7bc43b319a082987e20f7bf78f4bab80\_img.jpg\)](#)

**ex**  $0.600567 = \frac{0.424N*m}{0.706N*m}$



**16) Mechanical Power Developed in DC Motor given Input Power** ↗

**fx**  $P_m = P_{in} - (I_a^2 \cdot R_a)$

[Open Calculator ↗](#)

**ex**  $36.06592W = 78W - ((0.724A)^2 \cdot 80\Omega)$

**17) Motor Speed of DC Motor** ↗

**fx**  $N = \frac{60 \cdot n_{||} \cdot E_b}{Z \cdot n \cdot \Phi}$

[Open Calculator ↗](#)

**ex**  $1289.983\text{rev/min} = \frac{60 \cdot 6 \cdot 24.943V}{14 \cdot 4 \cdot 1.187Wb}$

**18) Motor Speed of DC Motor given Flux** ↗

**fx**  $N = \frac{V_s - I_a \cdot R_a}{K_f \cdot \Phi}$

[Open Calculator ↗](#)

**ex**  $1290.586\text{rev/min} = \frac{240V - 0.724A \cdot 80\Omega}{1.135 \cdot 1.187Wb}$

**19) Motor Torque given Mechanical Efficiency of DC Motor** ↗

**fx**  $\tau = \frac{\tau_a}{\eta_m}$

[Open Calculator ↗](#)

**ex**  $0.706667N*m = \frac{0.424N*m}{0.60}$



**20) Motor Torque of Series DC Motor given Machine Constant** ↗

$$fx \quad \tau = K_f \cdot \Phi \cdot I_a^2$$

[Open Calculator ↗](#)

$$ex \quad 0.706193N*m = 1.135 \cdot 1.187Wb \cdot (0.724A)^2$$

**21) Output Power given Overall Efficiency of DC Motor** ↗

$$fx \quad P_{out} = P_{in} \cdot \eta_o$$

[Open Calculator ↗](#)

$$ex \quad 36.66W = 78W \cdot 0.47$$

**22) Overall Efficiency of DC Motor** ↗

$$fx \quad \eta_o = \frac{P_m}{P_{in}}$$

[Open Calculator ↗](#)

$$ex \quad 0.461538 = \frac{36W}{78W}$$

**23) Overall Efficiency of DC Motor given Input Power** ↗

$$fx \quad \eta_o = \frac{P_{in} - (P_{cu(a)} + P_{cu(f)} + P_{loss})}{P_{in}}$$

[Open Calculator ↗](#)

$$ex \quad 0.417949 = \frac{78W - (1.25W + 2.81W + 41.34W)}{78W}$$



## 24) Supply Voltage given Electrical Efficiency of DC Motor ↗

**fx**  $V_s = \frac{\omega_s \cdot \tau_a}{I_a \cdot \eta_e}$

[Open Calculator ↗](#)

**ex**  $239.9963V = \frac{52.178\text{rev/s} \cdot 0.424\text{N*m}}{0.724\text{A} \cdot 0.8}$

## 25) Supply Voltage given Overall Efficiency of DC Motor ↗

**fx**  $V_s = \frac{(I - I_{sh})^2 \cdot R_a + L_m + P_{core}}{I \cdot (1 - \eta_o)}$

[Open Calculator ↗](#)

**ex**  $240.5996V = \frac{(0.658A - 1.58A)^2 \cdot 80\Omega + 9.1W + 6.8W}{0.658A \cdot (1 - 0.47)}$

## 26) Total Power Loss given Overall Efficiency of DC Motor ↗

**fx**  $P_{loss} = P_{in} - \eta_o \cdot P_{in}$

[Open Calculator ↗](#)

**ex**  $41.34W = 78W - 0.47 \cdot 78W$



## Variables Used

- $C_{loss}$  Constant Loss (Watt)
- $E_b$  Back EMF (Volt)
- $f$  Frequency (Hertz)
- $I$  Electric Current (Ampere)
- $I_a$  Armature Current (Ampere)
- $I_{sh}$  Shunt Field Current (Ampere)
- $K_f$  Constant of Machine Construction
- $L_m$  Mechanical Losses (Watt)
- $n$  Number of Poles
- $N$  Motor Speed (Revolution per Minute)
- $n_{||}$  Number of Parallel Paths
- $P_{conv}$  Converted Power (Watt)
- $P_{core}$  Core Losses (Watt)
- $P_{cu(a)}$  Armature Copper Loss (Watt)
- $P_{cu(f)}$  Field Copper Losses (Watt)
- $P_{in}$  Input Power (Watt)
- $P_{loss}$  Power Loss (Watt)
- $P_m$  Mechanical Power (Watt)
- $P_{out}$  Output Power (Watt)
- $R_a$  Armature Resistance (Ohm)
- $V_a$  Armature Voltage (Volt)



- $V_s$  Supply Voltage (*Volt*)
- $Z$  Number of Conductors
- $\eta_e$  Electrical Efficiency
- $\eta_m$  Mechanical Efficiency
- $\eta_o$  Overall Efficiency
- $T$  Motor Torque (*Newton Meter*)
- $T_a$  Armature Torque (*Newton Meter*)
- $\Phi$  Magnetic Flux (*Weber*)
- $\omega_s$  Angular Speed (*Revolution per Second*)



# Constants, Functions, Measurements used

- **Measurement:** Electric Current in Ampere (A)

*Electric Current Unit Conversion* 

- **Measurement:** Power in Watt (W)

*Power Unit Conversion* 

- **Measurement:** Frequency in Hertz (Hz)

*Frequency Unit Conversion* 

- **Measurement:** Magnetic Flux in Weber (Wb)

*Magnetic Flux Unit Conversion* 

- **Measurement:** Electric Resistance in Ohm ( $\Omega$ )

*Electric Resistance Unit Conversion* 

- **Measurement:** Electric Potential in Volt (V)

*Electric Potential Unit Conversion* 

- **Measurement:** Angular Velocity in Revolution per Second (rev/s),

Revolution per Minute (rev/min)

*Angular Velocity Unit Conversion* 

- **Measurement:** Torque in Newton Meter (N\*m)

*Torque Unit Conversion* 



## Check other formula lists

- DC Motor Characteristics Formulas 

- DC Series Motor Formulas 
- DC Shunt Motor Formulas 

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